

# AM 121: Intro to Optimization Models and Methods Fall 2018

## Lecture 9: Complementary Slackness



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### Lesson Plan

- **Complementary slackness:** a compatibility requirement between an optimal primal and an optimal dual solution.
- Stated for the standard inequality form.
- Used to reason about optimality, build intuitions. Motivates new family of algorithms.

Jensen & Bard: P127-128

# Complementary Slackness

(standard inequality form)

$$\max c^T x$$

$$\text{s.t. } Ax \leq b$$

$$x \geq 0$$

$$\min b^T y$$

$$\text{s.t. } A^T y \geq c$$

$$y \geq 0$$

- Vars dual  $\leftrightarrow$  constr. primal. Constr. dual  $\leftrightarrow$  vars in primal
- vars in one problem are “complementary” to constr. in other
- An inequality constraint “has slack” if it is not binding. A non-negativity constraint “has slack” if the variable is positive.
- **Complementary slackness:** cannot be slack in both a constraint and its associated variable.
- For example, if primal var  $> 0$  then the dual constr. is binding. If primal constr. not binding, then dual var = 0.

# Complementary Slackness

(standard inequality form)

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$$\text{s.t. } Ax \leq b$$

$$x \geq 0$$

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$$\text{s.t. } A^T y \geq c$$

$$y \geq 0$$

- Let  $s_1, \dots, s_m$  denote primal slack and  $e_1, \dots, e_n$  denote dual excess.
- **Theorem.** A primal feasible  $x$  and a dual feasible  $y$  are both **optimal** if and only if
 
$$x_j e_j = 0 \quad j = 1, \dots, n$$

$$y_i s_i = 0 \quad i = 1, \dots, m$$
- (primal var, dual constr.), (dual var, primal constr.)
- **“Cannot be slack in both.”**

# Intuition

$$\begin{array}{ll}
 \max c^T x & \min b^T y \\
 \text{s.t } Ax \leq b & \text{s.t } A^T y \geq c \\
 x \geq 0 & y \geq 0
 \end{array}$$

- Primal slack  $s_1, \dots, s_m$
- Complementary slackness:
 
$$y_i s_i = 0 \quad i = 1, \dots, m$$
 (dual var, primal constraint)
- If dual var positive, then primal constraint binding. (*Shadow price > 0 => scarce resources*).
- If primal constraint not binding, then dual var = 0. (*Surplus resources => shadow price = 0.*)

**Proof.** By definition of dual and primal, we have:

$$c^T x \leq (A^T y)^T x = y^T Ax \leq y^T b = b^T y$$

- First inequality can be written as:

$$\sum_j c_j x_j \leq \sum_j \left( \sum_i a_{ij} y_i \right) x_j \quad (*)$$

- In particular

$$c_j \leq \sum_i a_{ij} y_i$$

- If  $x$  solves **(P)** and  $y$  solves **(D)**,  $c^T x = b^T y$  {strong duality} and (\*) must be an equality.

- Since  $x_j \geq 0$  (all  $j$ ), for equality we need:

$$x_j > 0 \implies c_j = \sum_i a_{ij} y_i \quad j = 1, \dots, n$$

$$\text{and } (c_j < \sum_i a_{ij} y_i) \implies x_j = 0 \quad j = 1, \dots, n$$

- Equivalently:

$$x_j \left( \sum_i a_{ij} y_i - c_j \right) = 0 \quad \forall j = 1, \dots, n$$

$$\text{or, } x_j e_j = 0 \quad \forall j = 1, \dots, n$$

- This is the first CS condition.

**Proof.** By definition of dual and primal, we have:

$$c^T x \leq (A^T y)^T x = y^T Ax \leq y^T b = b^T y$$

- Similar analysis establishes  $y^T Ax = y^T b$  if and only if  $y_i s_i = 0 \quad \forall i = 1, \dots, m$

## Complementary Slackness

- $x_j e_j = 0 \quad j = 1, \dots, n$   
(jth primal var > 0)  $\implies$  (jth dual constr. binds) (1)  
(jth dual constr. slack)  $\implies$  (jth primal var = 0) (2)

**Note:** (1)  $\equiv$  (2)

- $y_i s_i = 0 \quad i = 1, \dots, m$   
(ith dual var > 0)  $\implies$  (ith primal constr. binds) (3)  
(jth primal constr. slack)  $\implies$  (ith dual var = 0) (4)

**Note:** (3)  $\equiv$  (4)

- Can work with whichever of (1) or (2), and (3) or (4) are most convenient

## Example: Comp. Slackness

$$\begin{array}{ll}
 \bullet \max x_1 - x_2 & \min 2y_1 - y_2 \\
 \text{s.t. } -3x_1 + x_2 \leq 2 & \text{s.t. } -3y_1 + 2y_2 \geq 1 \\
 2x_1 - x_2 \leq -1 & y_1 - y_2 \geq -1 \\
 x_1, x_2 \geq 0 & y_1, y_2 \geq 0
 \end{array}$$

(1) If  $x_1^* > 0$  in optimal primal solution, then first constraint in the optimal dual solution  $y^*$  is binding.

(4) If first constraint in optimal primal solution  $x^*$  is not binding, then variable  $y_1 = 0$  in optimal dual solution.

**Careful:** OK for both (var, constraint) pair to have zero slack;  
i.e. variables zero and constraint binding  
NOT OK for variable to be positive and constraint slack.

## Restricted Dual

- **Definition.** The **restricted dual RD(x)** problem given a feasible primal solution  $x$  modifies dual to impose CS conditions with respect to  $x$  in addition to dual feasibility.
- Any objective function can be adopted.
- **Theorem.** A feasible primal  $x$  is optimal if and only if the restricted dual **RD(x)** has a feasible solution.
- **Proof.**
- ( $\Rightarrow$ )  $x$  optimal  $\Rightarrow$  the optimal  $y$  satisfies CS with  $x \Rightarrow$  RD(x) is feasible.
- ( $\Leftarrow$ ) **RD(x)** is feasible  $\Rightarrow$  exists a dual solution  $y$  satisfying CS with  $x \Rightarrow$  both  $y$  and  $x$  are optimal.

## Example of RD (Furniture)

- Recall optimal  $x^*=(2, 0, 8, 24, 0, 0)$ ,  $z=280$
- Use (1) and (4) to impose constraints on dual, find feasible dual soln that satisfies CS:

$$x_1^* > 0 \implies e_1 = 0$$

$$x_3^* > 0 \implies e_3 = 0$$

$$s_1^* > 0 \implies y_1 = 0$$

- The dual LP is:

$$\begin{aligned} \min \quad & 48y_1 + 20y_2 + 8y_3 \\ \text{s.t.} \quad & 8y_1 + 4y_2 + 2y_3 \geq 60 \\ & 6y_1 + 2y_2 + 1.5y_3 \geq 30 \\ & y_1 + 1.5y_2 + 0.5y_3 \geq 20 \\ & y_1, y_2, y_3 \geq 0 \end{aligned}$$

- The **RD**( $x^*$ ) is:

$$\text{(since } e_1=0, y_1=0) \quad 4y_2 + 2y_3 = 60$$

$$\text{(since } e_3=0, y_1=0) \quad 1.5y_2 + 0.5y_3 = 20$$

$$\text{(since } y_1=0) \quad 2y_2 + 1.5y_3 \geq 30$$

Feasible  $y=(0, 10, 10, 0, 15, 0)$   
So,  $y$  and  $x^*$  are optimal.

## Primal-Dual Algorithms

- Can interpret the simplex method as maintaining **feasible primal** and an **infeasible dual** that satisfies CS conditions with **primal**. Terminates when **dual is feasible**  $\implies$  **primal** and **dual** are optimal.
- See this next lecture (along with the **dual simplex algorithm**).

*Properties maintained in each iteration*

	P feasible	D feasible	CS
P simplex	√	x	√
D simplex	x	√	√
primal-dual	√	√	x

## Summary: Complementary Slackness

- Stated for the standard inequality form.
- (P var, D con) (D var, P con). Cannot both have slack. In particular:
  - If **primal var**  $> 0$ , then associated **dual inequality** must be binding.
  - If **dual var**  $> 0$ , then associated **primal inequality** must be binding.
- Can also state the contrapositives:
  - If **dual inequality not binding**, then **primal var zero**
  - If **primal inequality not binding**, then **dual var zero**
- The restricted dual (**RD**):
  - Given primal  $x$ , impose CS, look for a feas **dual**
  - **Yes**:  $x$  is optimal. **No**:  $x$  is not optimal.